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Florian Grenouilleau Nadia Lahrichi Louis-Martin Rousseau

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Bureaux de Montréal : Université de Montréal Pavillon André-Aisenstadt C.P. 6128, succursale Centre-ville Montréal (Québec) Canada H3C 3J7 Téléphone : 514 343-7575 Télécopie : 514 343-7121

Bureaux de Québec : Université Laval Pavillon Palasis-Prince 2325, de la Terrasse, bureau 2642 Québec (Québec) Canada G1V 0A6 Téléphone: 418 656-2073 Télécopie : 418 656-2624

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Interuniversity Research Centre on Enterprise Networks, Logistics and Transportation (CIRRELT) and Department of Mathematics and Industrial Engineering, Polytechnique Montréal

Abstract. The continuous aging of the population and the desire of the elderly to stay in their own homes as long as possible has led to a considerable increase in the demand for home visits. Home care agencies try to serve more patients while maintaining a high level of service. They must regularly decide which patients they can accept and how the patients will be scheduled (care provider, visit days, visit times). In this paper we aim to maximize the number of new patients accepted while ensuring a single provider-to-patient assignment and a synchronization of the visit times for every patient. To solve this problem, we propose an extension to an existing logic-based Benders decomposition. Moreover, we present a new pattern-based logic-based Benders decomposition and a matheuristic using a large neighborhood search. The experiments demonstrate the efficiency of the proposed approaches and show that the matheuristic can solve all the benchmark instances in less than 20 seconds.

Keywords: Home care, scheduling, LBBD, matheuristic, LNS.

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^{*} Corresponding author: florian.grenouilleau@cirrelt.net

1. Introduction

Due to population aging and the government's plan to decentralize care, the demand for home care services has significantly increased during the last decade. These services allow the patients to stay in their own homes for as long as possible. From the government's point of view, home care services reduce the patient flow in hospitals and reduce the cost of care. Home care agencies continuously try to better manage their resources in order to serve more patients while maintaining a high level of service.

During the past ten years, many researchers have considered the routing and scheduling aspects of the problem (see Bertels & Fahle (2006), Nickel et al. (2012), Hiermann et al. (2015) and Grenouilleau et al. (2017)). The goal is to visit sets of patients while reducing costs (travel time, overtime) and/or maximizing soft constraints (patients' preferences, continuity of care). Recently, there have been two comprehensive surveys of the home health care routing and scheduling problem (Cissé et al., 2017; Fikar & Hirsch, 2017).

Home care agencies also wish to accept as many new patients as possible. This aspect of the problem has already been studied in the literature such as in (De Angelis, 1998) and (Koeleman et al., 2012). Heching et al. (2019) present a problem in which the goal is to schedule as many new patients as possible while taking into account those already present in the system (their visits cannot be rescheduled). In this challenging problem, only one care provider can be assigned to each patient, and the visit times must be the same over the entire horizon (one week). Moreover, restrictions on the travel times and the maximum working time of each provider must be respected. We refer to this as home care scheduling with predefined visits (HCS-PV).

Heching et al. (2019) proposed a logic-based Benders decomposition (LBBD) (Hooker & Ottosson, 2003).

The LBBD method has scalability issues. It is unable to solve some of the benchmark instances in a reasonable time (1 hour), and the time increases significantly with the difficulty of the instance. In this paper, we present three approaches based on decomposition methods that are able to solve all the benchmark instances while reducing the overall computational time.

Our contributions are as follows. We firstly propose a new algorithm for the subproblem of the LBBD formulation presented in Heching et al. (2019). It decomposes the subproblem to make it easier to solve. Secondly, we present a new LBBD formulation with additional variables. The new variables correspond to visit patterns for new patients; they combine the assigned provider, the visit days, and the visit times in a single variable so that most of the constraints can be handled in the master problem. Finally, we propose a new matheuristic method based on a Dantzig-Wolfe formulation (DWF) and a large neighborhood search (LNS). This matheuristic iteratively solves the problem using LNS and then solves the DWF using the providers' schedules found during the LNS iterations. Our computational experiments show that the matheuristic finds all the solutions of the benchmark instances in less than 20 seconds.

The remainder of this paper is as follows. Section 2 defines the problem. Section 3 presents the mathematical formulations, and Section 4 describes our matheuristic. Section 5 presents the computational results and Section 6 provides concluding remarks.

2. Problem definition

HCS-PV considers a patient set P and maximizes the number of scheduled patients given a set of available providers A. For each scheduled patient, we must determine the assigned provider, the visit days, and the visit time. These decisions must take into account the existing patients (called the "fixed" patients); the scheduled visits for the fixed patients cannot be modified. This constraint arises from the requirement for continuity of care. In the home care context, continuity of care involves always sending the same provider at the same time to the same patient, to build a relationship between them and to improve the patient's experience. Figure 1 gives an example of a provider's schedule and a possible slot for a new patient requiring two visits per week.

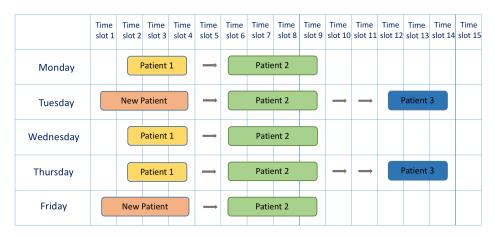


Figure 1: Possible assignment for a new patient requiring two visits per week.

Various assignment and routing constraints must be taken into account. Each patient is assigned to a single provider, and the visit times must be the same throughout the week (visit synchronization). There are also restrictions on the travel time, the available time windows for the patients and providers, and the maximum weekly working time for the providers. Formally, each patient p has a required number of visits $v_p \in [1, 5]$, a visit duration dur_p , a location l_p and a time window $[r_p, d_p]$ in which he/she must be visited. Moreover, some patients have special requirements, e.g., they may need a specified duration between visits. For this constraint we define the set K_p of possible day groups for patient p. Finally, each provider a has a location l_a with a service time equal to zero, a working time window $[r_a, d_a]$, and a maximum working time $\overline{W_a}$ over the week. The working time only comprises the time between the start of the first patient and the end of the last patient for each work day.

3. Mathematical formulations

In this section, we present three mathematical formulations. Firstly, we present the LBBD formulation (Heching et al., 2019) and propose an alternative subproblem. Secondly, we present another LBBD formulation based on visit patterns. Finally, we introduce a classical DWF.

3.1. Assignment-based LBBD

This first formulation (Heching et al., 2019) uses an LBBD (Hooker & Ottosson, 2003), which derives from the classical Benders decomposition (Benders, 1962). The classical Benders method decomposes the problem into two parts (master problem and subproblem). It iteratively solves the master problem and checks the feasibility and optimality of the solution in the subproblem. If necessary, the subproblem generates feasibility and/or optimality cuts, and these cuts are added to the master problem. The process stops when the generated solution is optimal or the problem is proved

infeasible. The Benders subproblems are linear programs, but in the LBBD the subproblem is a feasibility check based on the inference dual.

3.1.1. Master problem

In this first LBBD, the master problem corresponds to an assignment problem defining the visited patients and their visited days as well as the patient-provider assignments. We define three sets of decision variables: δ_p is 1 if patient p is visited and 0 otherwise; $x_{a,p}$ is 1 if patient p is visited by provider a and 0 otherwise; and $y_{a,p,d}$ is 1 if patient p is visited by provider a on day a. If there are restrictions on which days patients can be scheduled, we manage this with the constraint $p \in K$ where k = 0

The master problem (MP) is as follows:

$$(MP): \max \sum_{p \in P} \delta_p \tag{1}$$

s.t.
$$\sum_{a \in A} x_{a,p} = \delta_p \qquad \forall p \in P$$
 (2)

$$y_{a,p,d} \le x_{a,p}$$
 $\forall a \in A, \forall p \in P, \forall d \in D$ (3)

$$\sum_{a \in A} \sum_{d \in D} y_{a,p,d} = v_p \delta_p \qquad \forall p \in P$$
 (4)

$$x_{a,p} = 0$$
 $\forall a \in A, \forall p \in P, Q_p \nsubseteq Q_a$ (5)

$$y \in K \tag{6}$$

$$\delta_p, x_{a,p}, y_{a,p,k} \in \{0,1\} \quad \forall a \in A, \forall p \in P, \forall d \in D$$
 (7)

In the MP, the objective function (1) maximizes the number of patients visited. Constraints (2) and (3) link the variables, and constraints (4) enforce the required number of visits per patient. Constraints (5) ensure that special requirements are satisfied, and constraints (6) control the day groups allowed

for each patient. Finally, constraints (7) are the binary restrictions.

3.1.2. Subproblem

The subproblem determines if the assignment found by MP is feasible, if not, no-good cuts (on the $y_{a,p,d}$ variables) are added to the master problem. We define a subproblem SP for each provider. Each SP corresponds to a multiple-day traveling salesman problem with time windows, and it is solved using constraint programming. For each SP, we define $P_{(SP)}$ the set of assigned patients and $P_{(SP),d}$ the set of patients assigned per day d. In addition, we define sequencing variables $\pi_{d,v}$ that correspond to the patient p visited in the vth position on day d, with $p \in P_{(SP),d}$. These variables also take into account the fact that each route must start and end at the provider's location l_a . We also define the variables s_p corresponding to the visit time for patient p. Finally, we set the value V_P equal to $|P_{(SP),d}|$. We define a subproblem for each provider as follows:

$$(SP): \max 0 \tag{8}$$

s.t.
$$all_different\{\pi_{d,v}|v=1,...,V_P+2\}$$
 $\forall d \in D$ (9)

$$\pi_{d,1} = l_a, \pi_{d,V_P+2} = l_a \qquad \forall d \in D \tag{10}$$

$$r_p \le s_p \le d_p - dur_p$$
 $\forall p \in P_{(SP)}$ (11)

$$s_{\pi_{d,v}} + dur_{\pi_{d,v}} + t_{\pi_{d,v},\pi_{d,v+1}} \le s_{\pi_{d,v+1}} \quad \forall d \in D, v = 1, .., V_P + 1 \quad (12)$$

$$\sum_{d \in D} (s_{\pi_{d,V_P+1}} + dur_{\pi_{d,V_P+1}} - s_{\pi_{d,2}}) \le \overline{W_a}$$
(13)

$$\pi_{d,v} \in P_{(SP),d} \cup l_a \cup l_{a'}$$
 $\forall d \in D, v = 1, ..., V_P + 2$ (14)

In this formulation, the objective function (8) is 0 because we simply

want to verify if a solution exists. Constraints (9) are the patient sequencing constraints. Constraints (10) ensure that the provider starts and ends each day at his/her home, and constraints (11) enforce the patients' time windows. The travel time constraints are taken into account by constraints (12) and the maximum working time by constraints (13). The working time constraint measures the time between the start of the first patient and the end of the last one. Finally, the variables' domains are defined by constraints (14).

3.1.3. Alternative subproblem approach

The subproblem must consider all the routing constraints (travel time, visit synchronization, overtime, time windows) and this could lead to an excessive computational time. We therefore present an alternative approach. We first solve the problem for each day independently, without taking into account the provider's maximum weekly working time. If a feasible route is found for each day, we solve the full subproblem.

First, we introduce the constraint programming formulation of the daily problem in which the index d is removed. The daily subproblem (SP_d) is:

$$(SP_d): \max 0 \tag{15}$$

s.t.
$$all_different\{\pi_v|v=1,..,V_P+2\}$$
 (16)

$$\pi_1 = l_a, \pi_{V_P + 2} = l_a \tag{17}$$

$$r_p \le s_p \le d_p - dur_p$$
 $\forall p \in P_{(SP),d}$ (18)

$$s_{\pi_v} + dur_{\pi_v} + t_{\pi_v, \pi_{v+1}} \le s_{\pi_{v+1}} \qquad v = 1, .., V_P + 1$$
 (19)

$$\pi_v \in P_{(SP),d} \cup l_a \cup l_{a'}$$
 $v = 1, ..., V_P + 2$ (20)

Algorithm 1 gives the two-stage solution method.

Algorithm 1: Alternative subproblem

- ${f 1}$ for each day d of the horizon ${f do}$
- if (SP_d) is not feasible then
- 3 Generate a feasibility cut and stop the search;
- end if
- 5 end for
- 6 if Solve (SP) is not feasible then
- 7 Generate a feasibility cut and stop the search;
- s end if

3.2. Pattern-based LBBD

We must determine for each patient the assigned provider, the set of visit days, and the visit time. In the second formulation, we combine these decisions into a new variable.

We introduce the concept of a visit pattern ω , with four elements: patient p_{ω} , assigned provider a_{ω} , set of visit days D_{ω} , and visit time s_{ω} . The problem involves assigning a pattern $\omega \in \Omega_p$ to each patient, where Ω_p is a set containing all the visit patterns for patient p, with $\cup_{p \in P} \Omega_p = \Omega$. We can compute in advance the set of feasible patterns for each patient, thus generating the set Ω containing all the feasible patterns. Algorithm 2 generates the patterns.

Algorithm 2: Pattern Generation

```
1 \Omega = \emptyset; // List of the possible patterns;
 2 for each patient p do
 3
       for each provider a do
           for time index t \in [r_p, l_p] \cap [e_a, l_a] do
 4
               for each combination C of \binom{5}{v_p} days do
 5
                   if the pattern made of provider a, visit time t, and visit
 6
                    days C is feasible for patient p then
                       Add the pattern to \Omega;
 7
                   end if
 8
               end for
 9
           end for
10
       end for
11
12 end for
```

3.2.1. Master problem

We now present a new LBBD formulation based on Ω . Let the variable z_p be 1 if patient p is visited and 0 otherwise, and let x_{ω} be 1 if visit pattern ω is selected. Finally, $tt_{\omega,\omega'}$ corresponds to the travel time between the patient locations associated with patterns ω and ω' .

In the pattern-based formulation (PBF), the master problem is a set covering problem defined by (21)–(25). The objective function (21) maximizes the number of patients visited. Constraints (22) link the decision variables, and constraints (23) enforce the travel time between patients. Constraints (24)–(25) are the binary restrictions.

$$(PBF): \max \sum_{p \in P} z_p \tag{21}$$

s.t.
$$z_p = \sum_{\omega_p \in \Omega_p} x_{\omega_p}$$
 $\forall p \in P \quad (22)$

$$x_{\omega} + x_{\omega'} \le 1$$
 $\forall (\omega, \omega') \in \Omega, D_{\omega} \cap D_{\omega'} \ne \emptyset, s_{\omega} + tt_{\omega, \omega'} > s_{\omega'}$ (23)

$$z_p \in \{0, 1\} \qquad \forall p \in P \quad (24)$$

$$x_{\omega} \in \{0, 1\} \qquad \forall \omega \in \Omega \quad (25)$$

3.2.2. Subproblem

The new master problem includes all the constraints (single provider-to-patient assignment, synchronized visits, required number of visits, travel time, patient requirements) except the restrictions on the providers' working time, which are enforced in the subproblems. Algorithm 3 presents a simple polynomial algorithm for the solution of the subproblems.

Algorithm 3: Subproblem solution (for provider a)

- $1 \ sum_work_time = 0$;
- 2 for each day d of the horizon do
- **3** Retrieve the list L_d of assigned patterns containing this day;
- 4 Sort l_d by increasing order of visit times and build the route r_d ;
- 5 $sum_work_time += r_d$'s work time;
- 6 end for
- 7 if $sum_work_time > \overline{W_a}$ then
- 8 Create a no-good cut on the assigned patterns;
- 9 end if

3.3. Dantzig-Wolfe decomposition

In Section 3.2, each patient has an associated visit pattern, and so each provider has a list of assigned visit patterns corresponding to his/her weekly schedule. In this third formulation, we base our model on the providers' assignments. A feasible provider assignment corresponds to a subset of visit patterns that satisfies the travel and work-time constraints.

Let Λ be the set of feasible provider assignments, with Λ_a the set of feasible assignments for provider a. Let n_{λ} be the number of patients visited by assignment λ . We set $v_{\lambda,p}$ to 1 if patient p is visited by assignment λ and 0 otherwise. Finally, we define the decision variable x_{λ} , which is 1 if provider assignment λ is selected and 0 otherwise.

The assignment set partitioning formulation (ASP) is a Dantzig-Wolfe decomposition and is as follows:

$$(ASP): \max \sum_{\lambda \in \Lambda} n_{\lambda} x_{\lambda} \tag{26}$$

s.t.
$$\sum_{\lambda \in \Lambda_a} x_{\lambda} \le 1$$
 $\forall a \in A$ (27)

$$\sum_{\lambda \in \Lambda} v_{\lambda, p} x_{\lambda} \le 1 \qquad \forall p \in P \qquad (28)$$

$$x_{\lambda} \in \{0, 1\} \qquad \forall \lambda \in \Lambda \tag{29}$$

The objective function (26) maximizes the number of patients scheduled. Constraints (27) ensure that there is at most one assignment per provider, and constraints (28) ensure that there is at most one assignment per patient. Finally, constraints (29) are the binary restrictions.

4. Visit pattern matheuristic

In this section, we present a visit pattern matheuristic based on the formulation in Section 3.3 and an LNS. The LNS (Shaw, 1998) is a metaheuristic using the *ruin-and-recreate* principle (Schrimpf et al., 2000). This iterative method destroys part of the solution and then repairs it to improve its quality. The current and best solutions are then updated if necessary.

According to the literature, matheuristics provide a good balance between the solution quality of an exact method and the short computational time of metaheuristics. We have developed a visit pattern matheuristic (VPM) that uses an LNS to generate feasible provider assignments and then solves (26)–(29) using these assignments. Such a method has already been used in the home care context (Grenouilleau et al., 2017). In this paper, the set partitioning was on the daily routes while here we capture the provider's schedule for the entire horizon. We study the ability of this matheuristic to quickly generate interesting provider assignments, making it possible to find good solutions rapidly.

4.1. Overview of visit pattern metaheuristic

Algorithm 4 gives an overview of the VPM. We first create an initial solution and then iteratively remove part of the solution using a removal operator and rebuild it using a repair operator. We then analyze the temporary solution (S_t) to see if it improves the best found solution (S^*) or if the acceptance rule (simulated annealing in our context) accepts it as the current solution (S_i) . We solve the set partitioning problem based on Λ every 2000 iterations and update the current and best solutions if necessary.

The implementation details are given in Section 4.2

Algorithm 4: VPM

```
1 Create the initial solution S_c;
 2 Set the best found solution S^* to S_c;
 3 Create the empty set of provider assignments \Lambda;
 4 while termination criterion not met do
        S_t \leftarrow S_c;
        Apply removal operator to S_t;
        Apply repair operator to S_t;
        Add the assignments to \Lambda;
 8
       if S_t is accepted then
        S_c \leftarrow S_t;
10
        end if
11
        if S_t is better than S^* then
12
          S^* \leftarrow S_t;
13
        end if
14
        if total\_iteration \% 2000 = 0 then
15
           S_{sp} \leftarrow \text{Solve } ASP \text{ based on } \Lambda;
16
           if S_{sp} better than S^* then
18
20
        end if
\mathbf{21}
22 end while
```

4.2. Implementation details

We now present the implementation details of our LNS algorithm.

4.2.1. Initial solution

Algorithm 5 builds the initial solution using a greedy approach.

Algorithm 5: Initial Solution

- 1 Create P', a copy of the patient set P;
- **2** Create the solution S_i with fixed visit patterns per provider;
- 3 while P' is not empty do
- Randomly select patient p_t from P';
- 5 Remove p_t from P';
- **6** Find all the feasible insertions I_{p_t} for p_t 's visit patterns;
- 7 if I_{p_t} is not empty then
- 8 Apply to S_i the insertion giving the smallest increase in the travel time;
- 9 end if
- 10 return solution S_i ;

11 end while

4.2.2. Destroy and repair operators

We have adapted the classical removal and destroy operators from Shaw (1998) and Ropke & Pisinger (2006). These operators work on the feasible visit patterns described in Section 3.2. We list the operators here with brief descriptions. The removal operator (Ropke & Pisinger, 2006) removes q patients per iteration, and we set q to 30% of the number of scheduled patients. We define $C_{p,n}$ to be the increase in the travel time arising from the insertion of patient p's nth best option.

Random removal. This operator randomly selects q scheduled patients and removes their visit patterns from the solution.

Worst removal. This operator computes, for each patient, the improvement in the travel time if the patient's visit pattern is removed. It then removes the q patients with the highest values.

Related removal. This operator randomly selects a patient and removes his/her visit pattern. Then it removes the q-1 most closely related patients. In our implementation, the relation between two patients is based on the percentage of shared time windows and the required number of visits: $R(p,p') = \frac{[r_p,d_p] \cap [r_{p'},d_{p'}]}{d_p-r_p} + min(1,\frac{v_{p'}}{v_p}).$

Random repair. This operator randomly selects an unscheduled patient p, computes the possible insertions of p's visit patterns, and applies the insertion with the lowest cost. This operation is repeated until all the unscheduled patients have been tested.

Greedy repair. This operator iteratively computes the possible insertions for the unscheduled patients and applies the insertion associated with $argmin_{p \in P}C_{p,1}$. This operation is repeated until there are no more possible insertions.

Regret repair. This operator iteratively computes the possible insertions of the unscheduled patients and applies the best insertion for the patient with the highest regret value. Patient p's regret value is $C_{p,2} - C_{p,1}$.

4.2.3. Acceptance rule

The acceptance rule determines if the created solution can be accepted as the new current solution. It is based on simulated annealing as described in Ropke & Pisinger (2006). We set our initial temperature to $1.05 * f(S_i)$ and the decreasing temperature c to 0.99975.

4.2.4. Termination criteria

The termination of our LNS algorithm is based on two termination criteria: we stop after 20,000 iterations or 20 seconds of computation.

5. Computational results

In this section, we present experiments that analyze the efficiency of our alternative subproblem, the pattern-based formulation, and the matheuristic. We use the instances of Heching et al. (2019), and we have re-implemented their method, including their overtime and time-window relaxations. We refer to their formulation as *Heching*. Heching et al. (2019) provided 57 instances, each with 60 patients, those instances are split into three sets:

- Classical: Instances provided by their industrial partner;
- Narrow: Based on the Classical instances, with narrow patient time windows;
- Fewer: Based on the Classical instances, with fewer visits per patient.

We implemented the methods in C++ and performed the tests on a 2.7 GHz Intel Core i5 Macbook, with 16 Gb RAM and only one core. We solve the master problems (1)–(7) and (21)–(25) using Cplex 12.7.1 and the subproblems (8)–(14) and (15)–(20) using CP Optimizer. Finally, for the LBBDs, the maximum computational time is set to 3600 s per instance.

5.1. Efficiency of the LBBD formulations

We now analyze the impact of the alternative subproblem (3.1) and the pattern-based formulation (PBF). The results are given in Table 1. The first three columns present the instance name, the number of new patients

(a value of 6 indicates 6 new patients and 54 fixed patients), and the optimal solution. The CPU column gives the computational time in seconds. Finally, for PBF, Nb Pattern gives the number of feasible patterns computed and TL is the time limit $(3600 \, \text{s})$.

We observe that using the alternative subproblem dramatically reduces the computational time (-36.14%) and outperforms *Heching* for 51 of 55 solved instances. It performs especially well for the small and *Fewer* instances. In addition, according to Figure 2, *Heching'* subproblem has a failure rate (*Heching - Inf SP*) of 80.65% in average while the alternative subproblem only calls the whole subproblem (*Alternative - Call SP*) 30.70% of the time and the subproblem is infeasible (*Alternative - Inf SP*) only for 28.74% of those calls.

For the *Classical* and *Narrow* instances, the PBF dramatically outperforms the model proposed in Heching et al. (2019) even with the alternative subproblem. The PBF solves all the *Classical* instances in less than 9s and all the *Narrow* instances in less than 2s. However, for the *Fewer* instances, starting from 22 new patients, PBF does not outperform *Heching*. This is because of the increase in the generated patterns and therefore the size of the set partitioning problem. Nevertheless, PBF solves all the benchmark instances.

			Heching	Alt.	Subp.	PBF		
Instance	New Patients	Optimal Value	CPU (s)	CPU (s)	% Gap	CPU (s)	% Gap	Nb Pattern
Classic_8	8	60	1.05	0.59	-43.81%	0.01	-99.05%	277
Classic_9	9	59	0.96	0.71	-26.04%	0.01	-98.96%	276
Classic_10	10	59	1.34	0.83	-38.06%	0.02	-98.51%	358
Classic_11	11	59	1.26	1.15	-8.73%	0.02	-98.41%	405
Classic_12	12	59	1.53	1.42	-7.19%	0.02	-98.69%	441
Classic_13	13	59	2.12	0.85	-59.91%	0.05	-97.64%	551
Classic_14	14	58	8.85	5.75	-35.03%	0.11	-98.76%	690
Classic_15	15	58	8.79	6.30	-28.33%	0.11	-98.75%	724
Classic_16	16	58	14.27	6.06	-57.53%	0.16	-98.88%	865
Classic_17	17	59	12.81	11.54	-9.91%	0.45	-96.49%	1171
Classic_18	18	58	22.14	14.11	-36.27%	0.53	-97.61%	1214
Classic_19	19	58	31.93	30.79	-3.57%	0.87	-97.28%	1275
Classic_20	20	57	97.78	47.67	-51.25%	0.7	-99.28%	1325
Classic_21	21	58	210.34	86.18	-59.03%	1.2	-99.43%	1403
Classic_22	22	58	185.70	96.46	-48.06%	0.91	-99.51%	1535
Classic_23	23	58	1048.01	1557.68	48.63%	5.31	-99.49%	1913
Classic_24	24	58	TL	TL	/	5.32	/	2032
Classic_25	25	59	646.88	676.69	4.61%	3.3	-99.49%	2309
Classic_26	26	59	2088.62	532.45	-74.51%	8.44	-99.60%	2543
Fewer_12	12	58	1.25	1.03	-17.60%	0.07	-94.40%	998
Fewer_13	13	58	1.23	1.11	-9.76%	0.09	-92.68%	1158
Fewer_14	14	58	2.15	1.35	-37.21%	0.12	-94.42%	1230
Fewer_15	15	58	1.82	1.15	-36.81%	0.22	-87.91%	1584
Fewer_16	16	58	2.20	1.58	-28.18%	0.3	-86.36%	1671
Fewer_17	17	58	2.92	2.43	-16.78%	0.56	-80.82%	1989
Fewer_18	18	58	3.87	2.08	-46.25%	0.68	-82.43%	2109
Fewer_19	19	58	4.04	3.35	-17.08%	1.54	-61.88%	2484
Fewer_20	20	59	4.78	2.11	-55.86%	2.02	-57.74%	2645
Fewer_21	21	59	4.63	2.39	-48.38%	2.12	-54.21%	2954
Fewer_22	22	59	4.85	2.28	-52.99%	2.53	-47.84%	3459
Fewer_23	23	60	11.05	1.75	-84.16%	5.98	-45.88%	3693
Fewer_24	24	60	4.78	2.55	-46.65%	4.12	-13.81%	3991
Fewer_25	25	60	19.16	3.25	-83.04%	5.61	-70.72%	4536
Fewer_26	26	60	5.09	1.59	-68.76%	5.61	10.22%	4875
Fewer_27	27	60	21.70	4.27	-80.32%	29.74	37.05%	4950
Fewer_28	28	60	49.97	13.64	-72.70%	125.98	152.11%	5108
Fewer_29	29	59	78.30	21.17	-72.96%	83.68	6.87%	5196
Fewer_30	30	59	398.6	221.64	-44.40%	3530.71	785.78%	5318
Narrow_8	8	60	0.95	0.67	-29.47%	0.01	-98.95%	243
Narrow_9	9	59	1.33	0.88	-33.83%	0.01	-99.25%	242
Narrow_10	10	59	1.67	0.75	-55.09%	0.01	-99.40%	296
Narrow_11	11	59	1.29	0.79	-38.76%	0.01	-99.22%	308
Narrow_12	12	59	0.97	1.03	6.19%	0.01	-98.97%	348
Narrow_13	13	59	2.16	0.98	-54.63%	0.02	-99.07%	394
Narrow_14	14	59	4.51	4.25	-5.76%	0.04	-99.11%	543
Narrow_15	15	59	4.08	2.20	-46.08%	0.04	-99.02%	568
Narrow_16	16	59	6.80	3.80	-44.12%	0.08	-98.82%	692
Narrow_17	17	59	7.38	4.50	-39.02%	0.14	-98.10%	823
Narrow_18	18	58	14.90	7.58	-49.13%	0.24	-98.39%	842
Narrow_19	19	58	17.81	11.41	-35.93%	0.25	-98.60%	846
Narrow_20	20	57	23.46	25.05	6.78%	0.49	-97.91%	860
Narrow_21	21	57	34.24	25.47	-25.61%	0.54	-98.42%	878
Narrow_22	22	57	73.74	68.79	-6.71%	0.5	-99.32%	948
Narrow_23	23	58	190.47	129.74	-31.88%	1.23	-99.35%	1212
Narrow_24	24	58	674.33	401.60	-40.44%	1.13	-99.83%	1317
Narrow_25	25	58	TL	TL	/	1.38	/	1452
Narrow_26	26	59	1303.29	1169.51	-10.26%	1.89	-99.85%	1594
Na110W_20			1000.20	1100.01		1.00	00.0070	

Table 1: Results for the alternative subproblem and visit pattern formulation

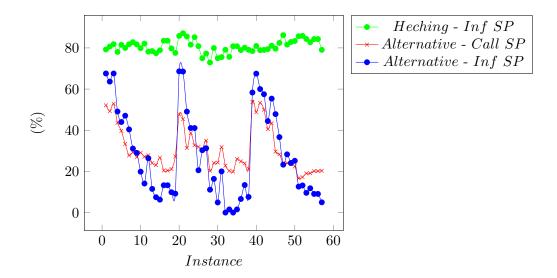


Figure 2: Comparison of the failure rates during the full subproblems resolutions

5.2. Efficiency of the matheuristic

In this section, we test the visit pattern matheuristic (VPM) proposed in Section 4. To do this, we solve the instances with the classical LNS (i.e., without set partitioning) and with the VPM. The results are given in Table 2. The columns Best and CPU Best correspond to the best found solution and the time (in seconds) at which this solution was found. The LNS solves 37 of the 57 instances in less than 20 s or 20,000 iterations. With the same termination criteria, the VPM solves all the instances. For most of the instances (51), the VPM finds the best solution in the first 10 s.

				LNS			VPM	
Instance	New Patients	Optimal Value	Best Value	CPU (s)	CPU Best (s)	Best Value	CPU (s)	CPU Best (s)
Classic_8	8	60	60	8.3	0.06	60	8.44	0.06
Classic_9	9	59	59	8.32	0.16	59	8.44	0.16
Classic_10	10	59	59	9.18	0.01	59	9.59	0.01
Classic_11	11	59	59	11.85	0.11	59	12.1	0.11
Classic_12	12	59	59	13.41	0.01	59	13.99	0.01
Classic_13	13	59	59	16.21	0.03	59	14.92	0.03
Classic_14	14	58	58	19.03	0.05	58	18.76	0.05
Classic_15	15	58	58	18.51	0.03	58	18.92	0.03
Classic_16	16	58	58	20	0.06	58	20	0.06
Classic_17	17	59	59	20	17.03	59	20	4.16
Classic_18	18	58	58	20	0.70	58	20	0.75
Classic_19	19	58	58	20	3.12	58	20	3.17
Classic_20	20	57	57	20	0.02	57	20	0.03
Classic_21	21	58	57	20	5.53	58	20	10.49
Classic_22	22	58	57	20	4.01	58	20	5.58
Classic_23	23	58	57	20	1.12	58	20	6.88
Classic_24	24	58	58	20	3.50	58	20	3.52
Classic_25	25	59	58	20	8.35	59	20	16.18
Classic_26	26	59	57	20	0.68	59	20	9.14
Fewer_12	12	58	58	20	0.16	58	20	0.16
Fewer_13	13	58	58	20	0.04	58	20	0.04
Fewer_14	14	58	58	20	0.02	58	20	0.01
Fewer_15	15	58	58	20	1.01	58	20	1.03
Fewer_16	16	58	58	20	0.09	58	20	0.09
Fewer_17	17	58	58	20	0.09	58	20	0.10
Fewer_18	18	58	58	20	0.15	58	20	0.15
Fewer_19	19	58	58	20	1.04	58	20	1.04
Fewer_20	20	59	58	20	0.25	59	20	6.29
Fewer_21	21	59	59	20	1.69	59	20	1.96
Fewer_22	22	59	59	20	5.26	59	20	4.83
Fewer_23	23	60	59	20	0.16	60	20	8.79
Fewer_24	24	60	60	20	0.84	60	20	0.80
Fewer_25	25	60	60	20	16.66	60	20	9.61
Fewer_26	26	60	60	20	12.62	60	20	10.41
Fewer_27	27	60	59	20	0.29	60	20	11.19
Fewer_28	28	60	59	20	3.84	60	20	12.2
Fewer_29	29	59	59	20	9.99	59	20	9.45
Fewer_30	30	59	58	20	7.55	59	20	13.93
Narrow_8	8	60	60	8.22	0.03	60	7.09	0.03
Narrow_9	9	59	59	8.23	0.25	59	8.00	0.24
Narrow_10	10	59	59	9.79	0.18	59	9.86	0.18
Narrow_11	11	59	59	9.97	0.02	59	10.98	0.22
Narrow_12	12	59	59	11.67	0.79	59	11.39	0.78
Narrow_13	13	59	59	12.57	0.11	59	12.51	0.11
Narrow_14	14	59	58	14.94	0.01	59	14.86	1.73
Narrow_15	15	59	58	15.65	0.97	59	16.17	1.81
Narrow_16	16	59	58	20	0.18	59	20	2.28
Narrow_17	17	59	58	20	0.68	59	20	2.73
Narrow_18	18	58	58	20	10.59	58	20	2.98
Narrow_19	19	58	57	20	1.68	58	20	3.30
Narrow_20	20	57	56	20	0.62	57	20	3.47
Narrow_21	21	57	56	20	0.74	57	20	3.49
Narrow_22	22	57	57	20	16.93	57	20	3.67
Narrow_23	23	58	57	20	11.72	58	20	9.35
Narrow_24	24	58	57	20	11.86	58	20	10.46
Narrow_25	25	58	58	20	8.39	58	20	5.48
Narrow_26	26	59	57	20	1.81	59	20	13.46
Average				17.82	3.05		17.84	3.83

Table 2: Results for the matheuristic

6. Conclusions

The HHC-PV is a complex problem that home care agencies have to solve every day. The goal is to assign and schedule a set of new patients given a set of providers while taking into account the patients already present in the system. Each patient has a required number of visits and can be assigned to only one provider. The visit times must be the same for the entire horizon, and each provider has a maximum working time.

To solve this problem, we have extended the work of (Heching et al., 2019). First, we proposed an alternative two-stage subproblem. Then, we presented a new LBBD based on visit patterns that includes more constraints in the master problem. Finally, we introduced a Dantzif-Wolfe formulation and developed a matheuristic based on LNS.

Our computational experiments show that our alternative subproblem reduces the average computational time by 34%, while the new pattern-based formulation solves all the benchmark instances, usually in less than 10 s. Finally, our matheuristic solves all the instances in less than 20 s.

In future research, we plan to take into account more practical constraints and to analyze how our formulations perform in such contexts.

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